```
2020-07-24 22:52:03.454 - info: robonect.0 (19104) Polling done
2020-07-24 22:52:09.320 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":73,"method":"get_status"}
2020-07-24 22:52:09.320 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1027,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":73}
2020-07-24 22:52:09.320 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":74,"method":"get_status"}
2020-07-24 22:52:29.321 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":75,"method":"miIO.info"}
2020-07-24 22:52:29.322 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:53
2020-07-24 22:52:29.331 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":75,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17026}}
2020-07-24 22:52:29.339 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1028,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":74}
2020-07-24 22:52:49.323 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":76,"method":"get_status"}
2020-07-24 22:52:49.332 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1029,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":76}
2020-07-24 22:53:03.477 - info: robonect.0 (19104) Polling done
2020-07-24 22:53:09.324 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":77,"method":"get_status"}
2020-07-24 22:53:09.335 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1030,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":77}
2020-07-24 22:53:29.324 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":78,"method":"get_status"}
2020-07-24 22:53:29.325 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":79,"method":"miIO.info"}
2020-07-24 22:53:29.326 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:54
2020-07-24 22:53:29.335 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":79,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17088}}
2020-07-24 22:53:29.336 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1031,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":78}
2020-07-24 22:53:47.218 - debug: mihome-vacuum.0 (9587) stateChange mihome-vacuum.0.map.loadMap {"val":true,"ack":false,"ts":1595624027215,"q":0,"from":"system.adapter.admin.0","user":"system.user.admin","lc":1595604062333}
2020-07-24 22:53:47.219 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":80,"method":"get_map_v1"}
2020-07-24 22:53:47.227 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":["retry"],"id":80}
2020-07-24 22:53:47.729 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":81,"method":"get_map_v1"}
2020-07-24 22:53:47.729 - debug: mihome-vacuum.0 (9587) 0. Mappointer_nomap___retry
2020-07-24 22:53:47.736 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":["tanos%2F262038791%2F7"],"id":81}
2020-07-24 22:53:47.737 - debug: mihome-vacuum.0 (9587) Mappointer_updated
2020-07-24 22:53:49.325 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":82,"method":"get_status"}
2020-07-24 22:53:49.334 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1032,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":82}
2020-07-24 22:54:03.477 - info: robonect.0 (19104) Polling done
2020-07-24 22:54:09.326 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":83,"method":"get_status"}
2020-07-24 22:54:09.338 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1033,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":83}
2020-07-24 22:54:29.328 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":84,"method":"get_status"}
2020-07-24 22:54:29.329 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":85,"method":"miIO.info"}
2020-07-24 22:54:29.330 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:55
2020-07-24 22:54:29.337 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":85,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17148}}
2020-07-24 22:54:29.340 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1034,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":84}
2020-07-24 22:54:49.329 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":86,"method":"get_status"}
2020-07-24 22:54:49.339 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1035,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":86}
2020-07-24 22:55:00.025 - info: host.iobroker instance system.adapter.darksky.0 started with pid 16718
2020-07-24 22:55:01.655 - info: darksky.0 (16718) starting. Version 0.2.1 in /opt/iobroker/node_modules/iobroker.darksky, node: v12.18.2, js-controller: 3.1.6
2020-07-24 22:55:01.680 - info: darksky.0 (16718) [START] Starting DarkSky adapter
2020-07-24 22:55:03.483 - info: robonect.0 (19104) Polling done
2020-07-24 22:55:04.043 - info: host.iobroker instance system.adapter.dwd.0 started with pid 16782
2020-07-24 22:55:06.790 - info: dwd.0 (16782) starting. Version 2.4.10 in /opt/iobroker/node_modules/iobroker.dwd, node: v12.18.2, js-controller: 3.1.6
2020-07-24 22:55:07.424 - info: darksky.0 (16718) [END] Stopping DarkSky adapter...
2020-07-24 22:55:07.429 - info: darksky.0 (16718) Terminated (NO_ERROR): Without reason
2020-07-24 22:55:07.537 - info: dwd.0 (16782) Terminated (NO_ERROR): Without reason
2020-07-24 22:55:07.948 - info: host.iobroker instance system.adapter.darksky.0 terminated with code 0 (NO_ERROR)
2020-07-24 22:55:08.058 - info: host.iobroker instance system.adapter.dwd.0 terminated with code 0 (NO_ERROR)
2020-07-24 22:55:09.331 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":87,"method":"get_status"}
2020-07-24 22:55:09.339 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1036,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":87}
2020-07-24 22:55:29.332 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":88,"method":"get_status"}
2020-07-24 22:55:29.332 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":89,"method":"miIO.info"}
2020-07-24 22:55:29.333 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:56
2020-07-24 22:55:29.341 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":89,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17208}}
2020-07-24 22:55:29.342 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1037,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":88}
2020-07-24 22:55:46.975 - info: robonect.0 (19104) Polling done
2020-07-24 22:55:49.334 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":90,"method":"get_status"}
2020-07-24 22:55:49.343 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1038,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":90}
2020-07-24 22:56:02.596 - debug: mihome-vacuum.0 (9587) system.adapter.admin.0: logging false
2020-07-24 22:56:03.495 - info: robonect.0 (19104) Polling done
2020-07-24 22:56:09.334 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":91,"method":"get_status"}
2020-07-24 22:56:09.344 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1039,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":91}
2020-07-24 22:56:29.335 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":92,"method":"get_status"}
2020-07-24 22:56:29.336 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":93,"method":"miIO.info"}
2020-07-24 22:56:29.337 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:57
2020-07-24 22:56:29.347 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":93,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17268}}
2020-07-24 22:56:29.348 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1040,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":92}
2020-07-24 22:56:49.337 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":94,"method":"get_status"}
2020-07-24 22:56:49.357 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1041,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":94}
2020-07-24 22:57:03.503 - info: robonect.0 (19104) Polling done
2020-07-24 22:57:09.339 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":95,"method":"get_status"}
2020-07-24 22:57:09.356 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1042,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":95}
2020-07-24 22:57:29.340 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":96,"method":"get_status"}
2020-07-24 22:57:29.341 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":97,"method":"miIO.info"}
2020-07-24 22:57:29.342 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:58
2020-07-24 22:57:29.349 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":97,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17328}}
2020-07-24 22:57:29.350 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1043,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":96}
2020-07-24 22:57:49.341 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":98,"method":"get_status"}
2020-07-24 22:57:49.353 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1044,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":98}
2020-07-24 22:58:03.509 - info: robonect.0 (19104) Polling done
2020-07-24 22:58:09.344 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":99,"method":"get_status"}
2020-07-24 22:58:09.361 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1045,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":99}
2020-07-24 22:58:21.259 - debug: mihome-vacuum.0 (9587) system.adapter.admin.0: logging true
2020-07-24 22:58:29.347 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":100,"method":"get_status"}
2020-07-24 22:58:29.348 - debug: mihome-vacuum.0 (9587) sendMsg[1] >>> {"id":101,"method":"miIO.info"}
2020-07-24 22:58:29.349 - debug: mihome-vacuum.0 (9587) Next WiFi check: 24.07 22:59
2020-07-24 22:58:29.357 - debug: mihome-vacuum.0 (9587) Receive <<< {"partner_id":"","id":101,"code":0,"message":"ok","result":{"hw_ver":"Linux","fw_ver":"3.5.8_2076","ap":{"ssid":"IPZ-Fritz","bssid":"f0:b0:14:ec:c0:dd","rssi":-70},"netif":{"localIp":"192.168.2.81","mask":"255.255.255.0","gw":"192.168.2.1"},"miio_ver":"miio-
client 3.5.8","model":"roborock.vacuum.s6","mac":"50:EC:50:1D:A9:E0","token":"44705a675969364445 4a7151726a7637","life":17388}}
2020-07-24 22:58:29.360 - debug: mihome-vacuum.0 (9587) Receive <<< {"result":
[{"msg_ver":2,"msg_seq":1046,"state":8,"battery":100,"clean_time":29,"clean_area":662500,"error_code":0,"map_present":1,"in_cleaning":0,"in_returning":0,"in_fresh_state":1,"lab_status":1,"water_box_status":0,"fan_power":102,"dnd_enabled":0,"map_status":3,"is_locating":0,"lock_status":0,"mop_forbidden_enable":0}],"id":100}
```